



# Remember the connections!

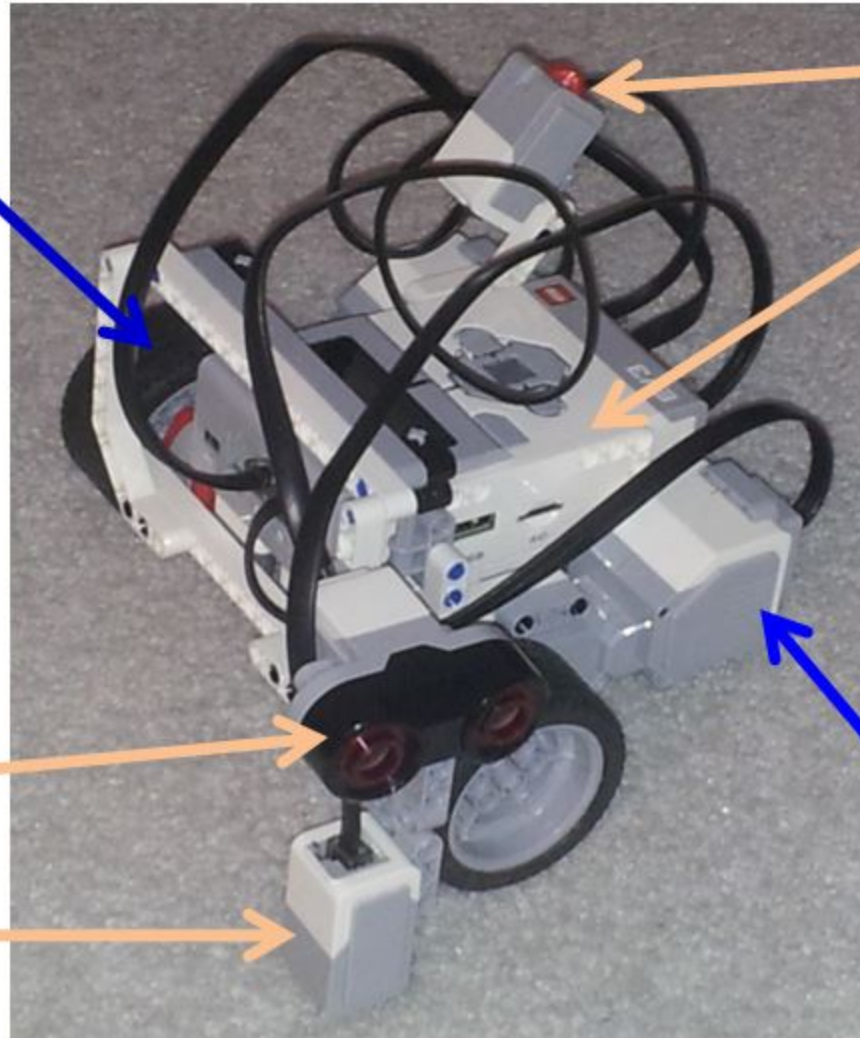
- Left Motor connects to **B**
- Right Motor connects to **C**
  - If your motors are upside down forward will be backwards in your program
- Color sensor connects to port no. **1**
- Touch sensor connects to port no. **2**
- Sonar sensor connects to port no. **4**

Please note that the retail version of EV3 uses an infrared sensor, not a sonar sensor.



# Lego NXT robot used – Omnibot

Right Motor: C



Touch Sensor

EV3 Brick

Sonar Sensor

Color Sensor

Left Motor: B