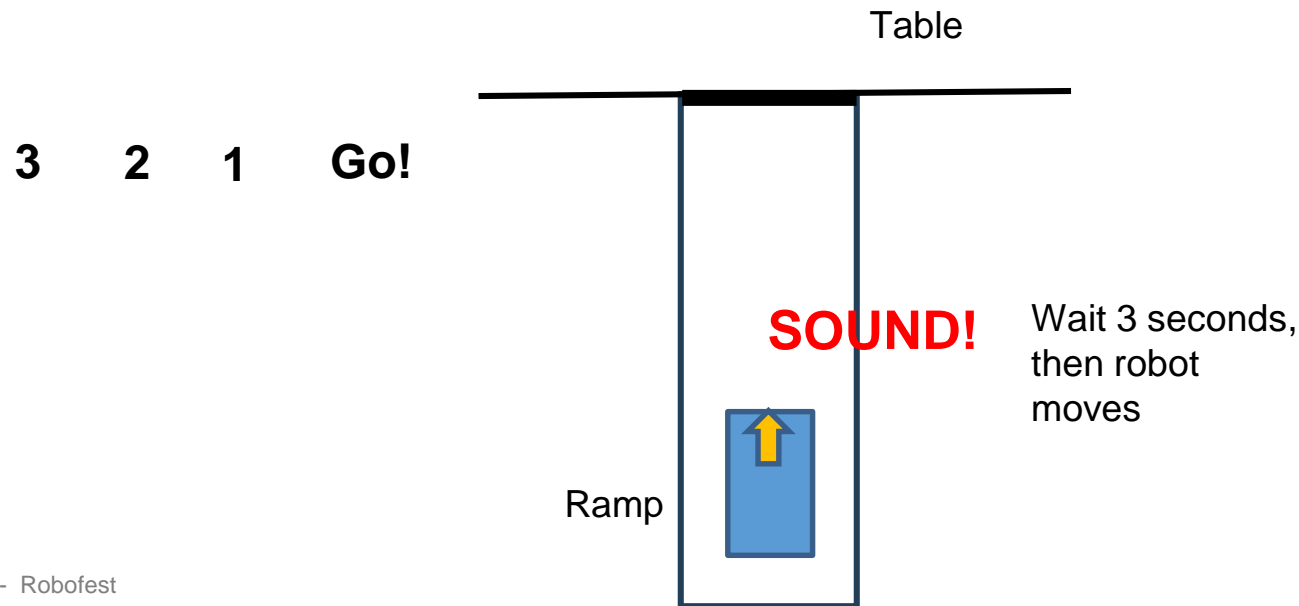


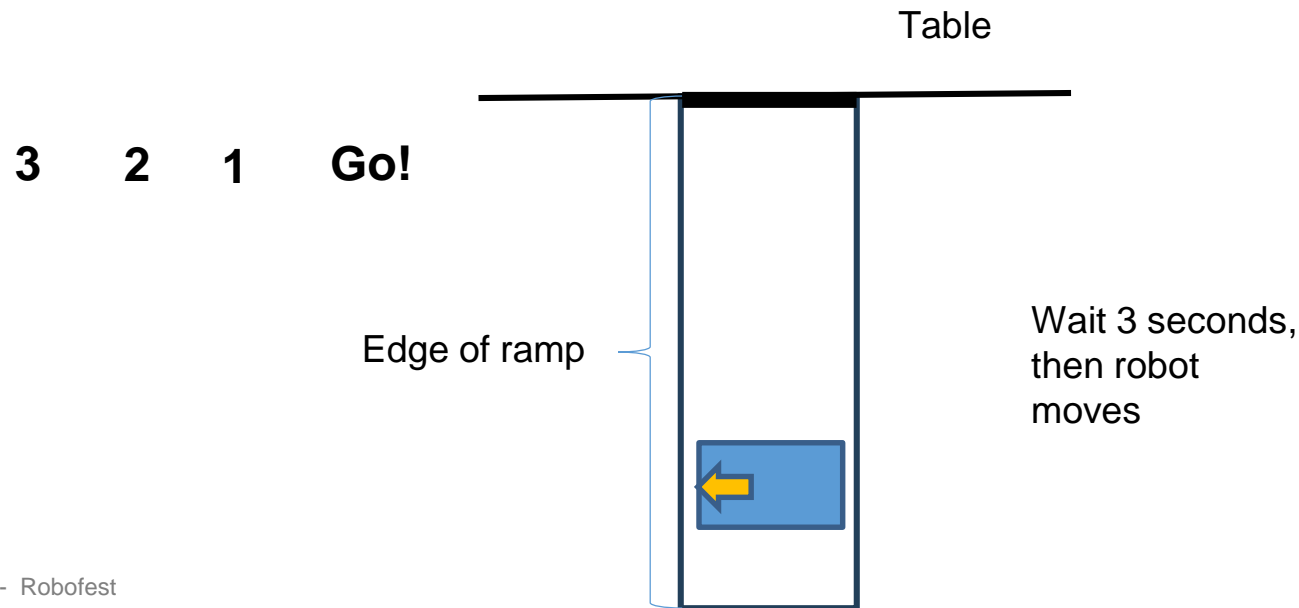
# Unknown Start Example 1

- Front of robot faces the top of the ramp
- Robot must be able to start anywhere on the ramp. Exact location will be unveiled after impound
- When started, robot make a sound, then wait 3 seconds before continuing



# Unknown Start Example 2

- Front of robot faces left ramp edge approximately 2 cm away
- Robot must be able to start anywhere along the straight edge. Exact location will be unveiled before each round
- When started, robot must turn right and wait 3 seconds before continuing



# Unknown Start Example 3

- Front of robot faces the top of the ramp
- Robot must be able to start anywhere along the straight edge. Exact location will be unveiled before each round
- Robot must wait until your hand is held in front of the object sensor, then turn right and wait 3 seconds before continuing

