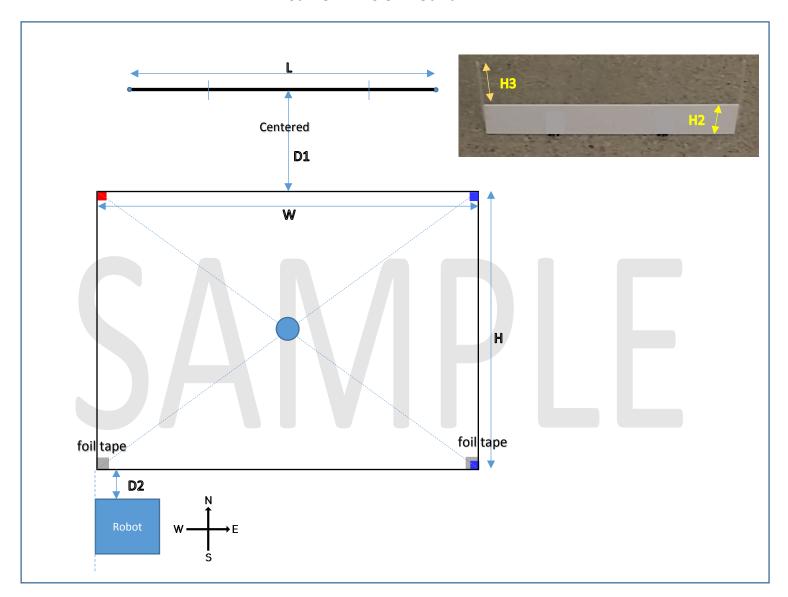


## **Unknown Factors – EXAMPLE**

## **Junior Division Round 1**



D1 = 40cm

Robot Starting Orientation = N

**Note**: Teams may measure L, W, H, H2 and H3 values during the work-time. These values will not change throughout the day.

D3 (Trash Objects) will be set after all robots are impounded.